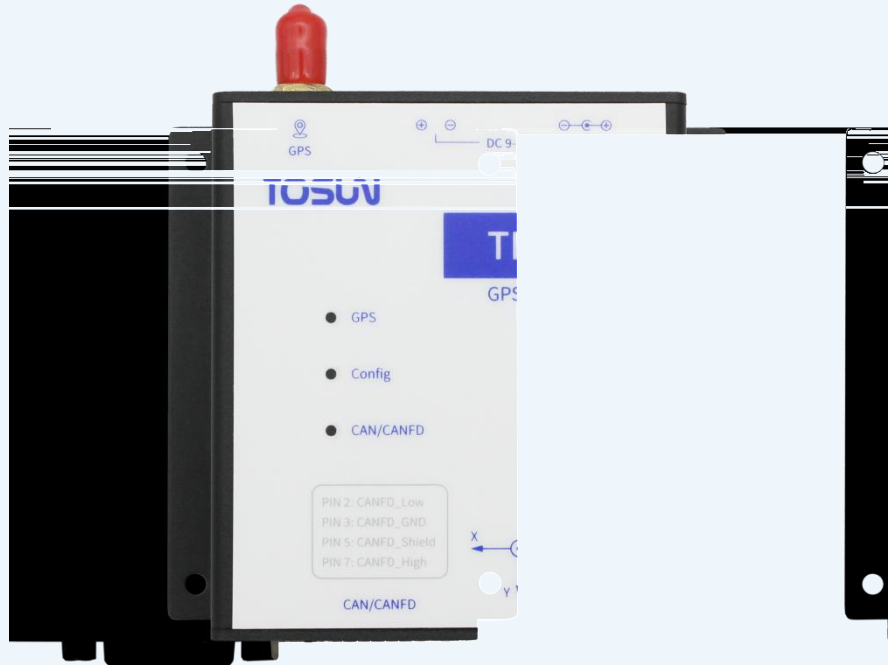


TOSUN



70 3URGXFW 0DQXDC

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WRVXQDL FRP

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:K\ ,V D - W 3 \$ 1 'HYLFH 1 HFHVVDU\

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\$ERXW WKL V 8VHU 0DQXDO

:DUUDQW\

&RS\ULJKW

70

2YHUYLHZ



) HDWXUHV

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7HFKQLFDO 'DWD

✓

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	- ~
	~ (non-condensing)

✓

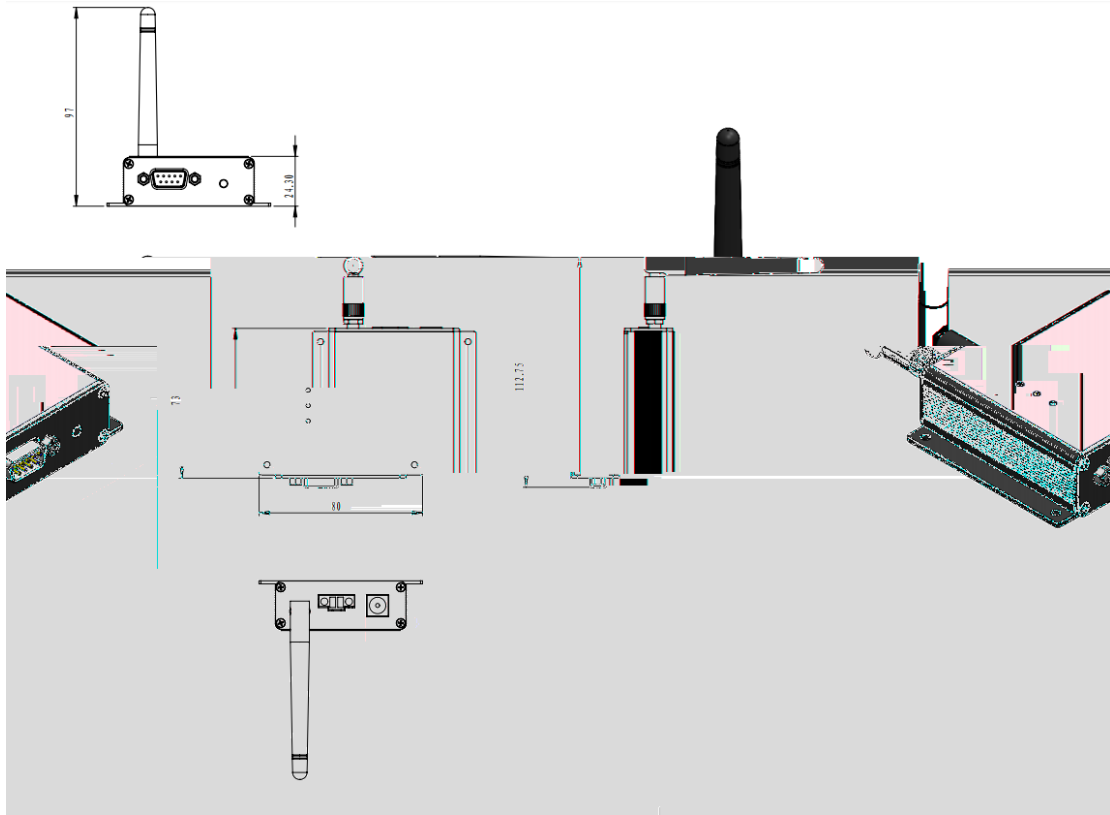
✓

(OHFWULFDO 'DWD

		Test Condition	Minimum Value	Typical Value		
	External DC power supply	CAN transmission				
	External DC power supply	CAN transmission	--		--	
	External DC power supply	CAN transmission	--		--	

Bus pin
voltage
CAN
Interface
resistance

0HFKDQLFDO 'DWD



6FRSH RI 'HOLYHU\

✓

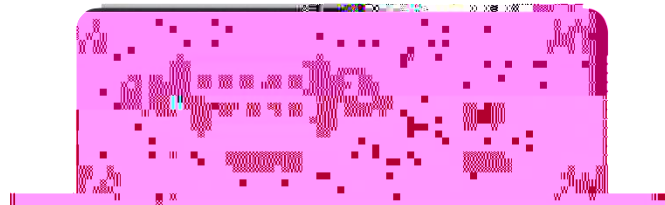
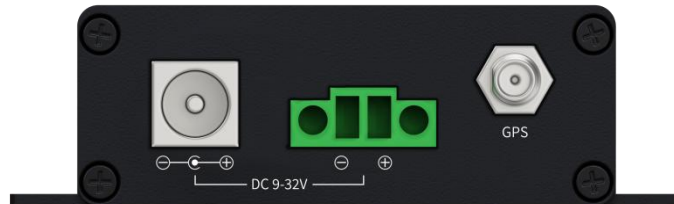
✓



✓



+DUGZDUH ,QWHUIDFH



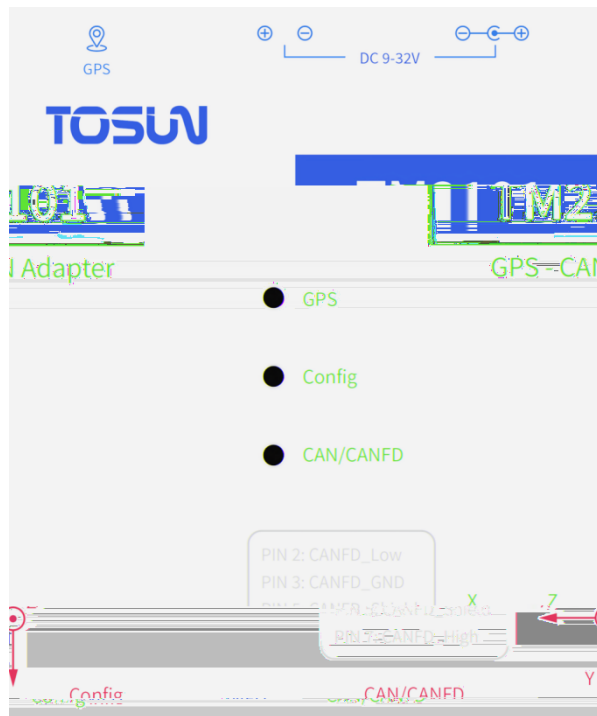
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'% 3L	3,1	'HILQLWL
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	1 X PEH	

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✓



✓

, QGLFDV 'HILQLWLRG

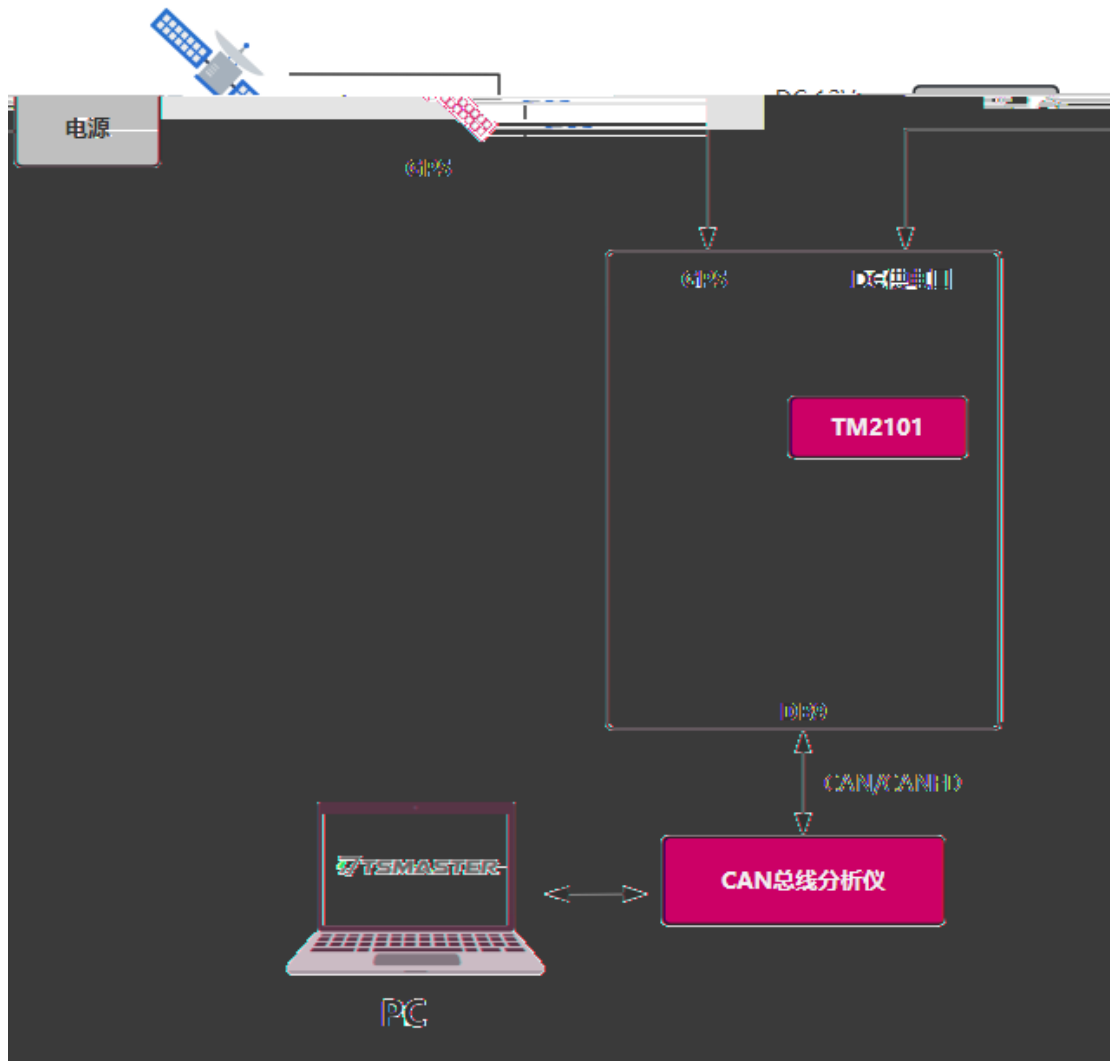
✓

, QGLFDV 'HVFULSWLRQ

2SWLRQDO \$FFHVVRULHV

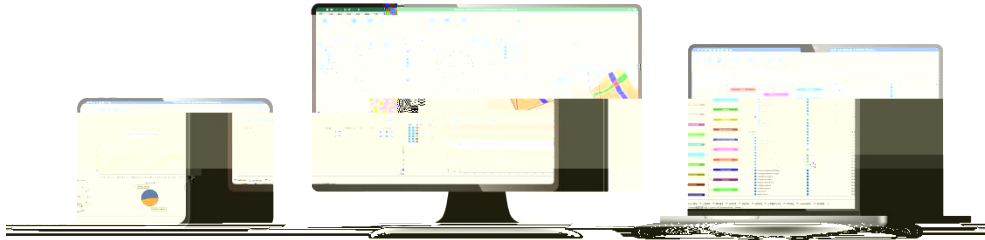
4XLFN 6WDUW

6\ VWHP & RQQHFWLRQ

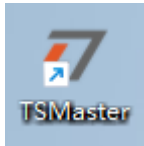


'ULYHU ,QVWDOODWLRQ

6RIWZDUH 2YHUYLHZ



6RIWZDUH ,QVWDOODWLRQ



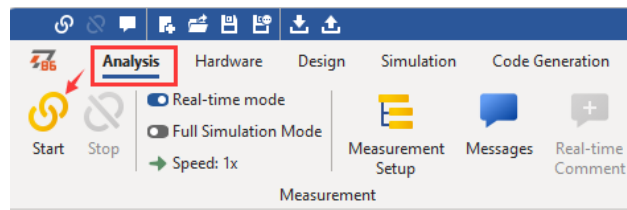
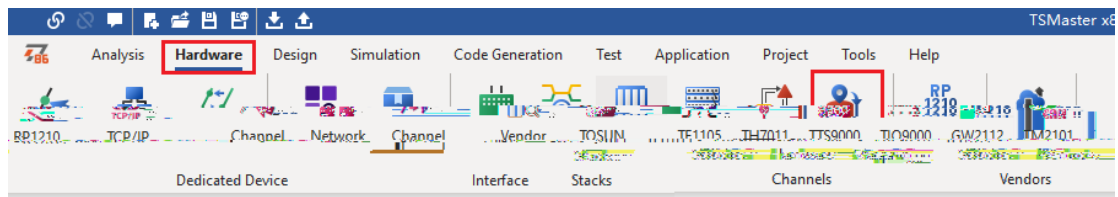
)XQFWDRGXOH

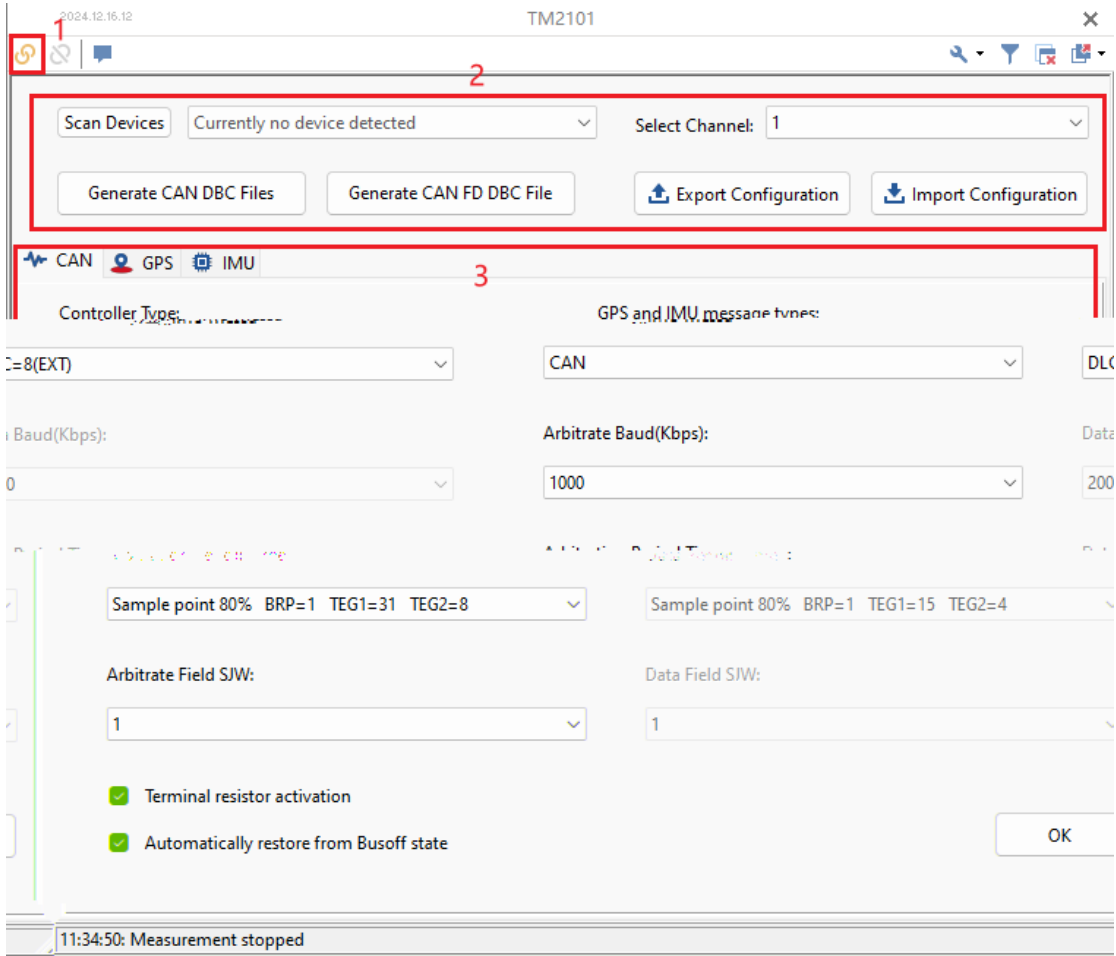
)XPRGH 3RVLWLRQLQJ DQG 1DYLJDWLRQ ORGXOH

*\URVFRSH DQG \$FFHOHURPHWHU

)XQGDPHQWDO 8VDJH

%DVLF ,QWURGXFWRQ





(1)

(2)



(1)

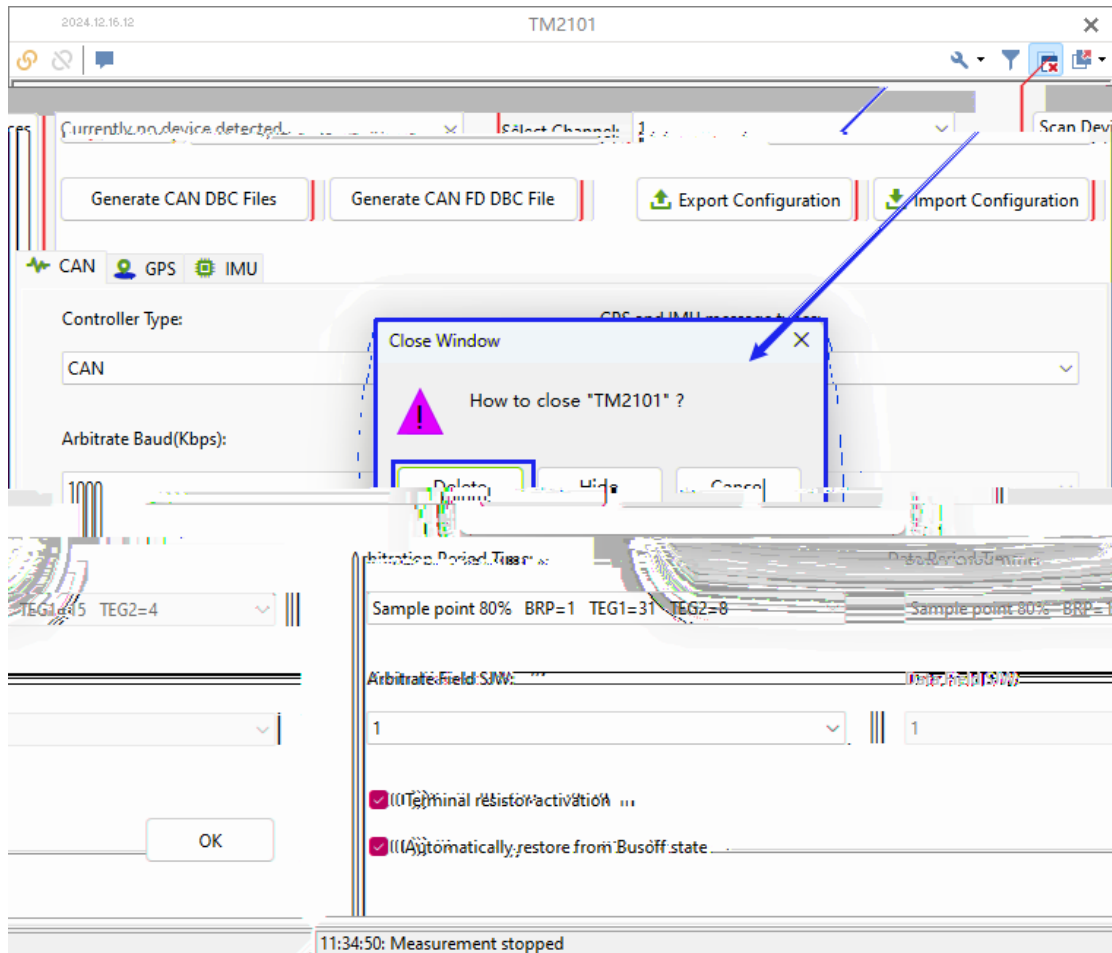
(2)

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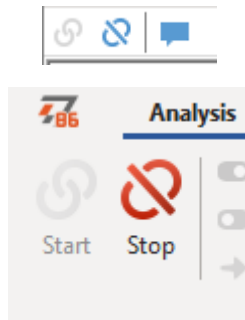
?



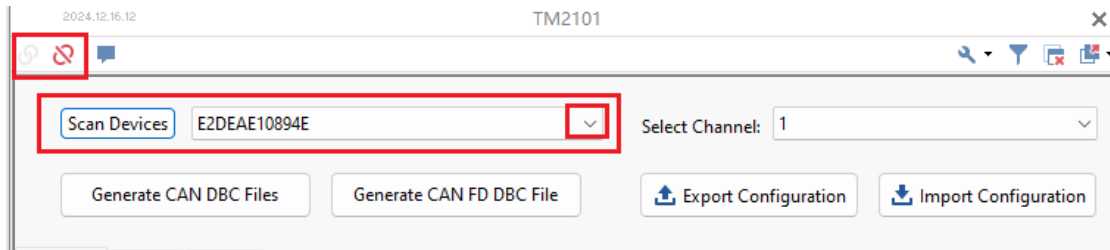
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- (1)
- (2)
- (3)

'HWDLOWGRGXFWLRQ

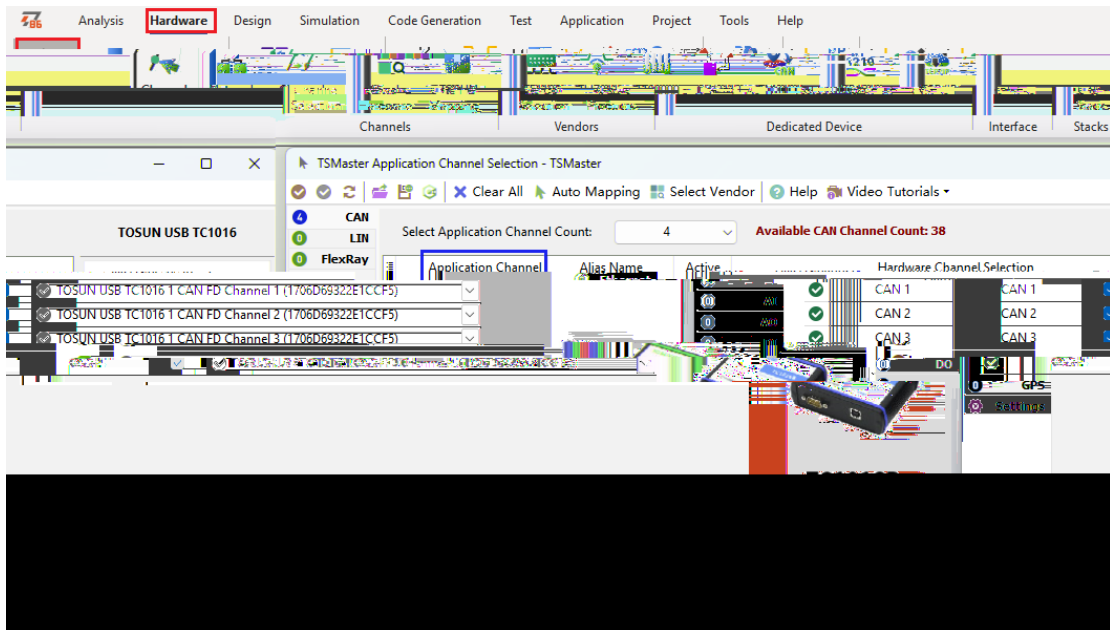
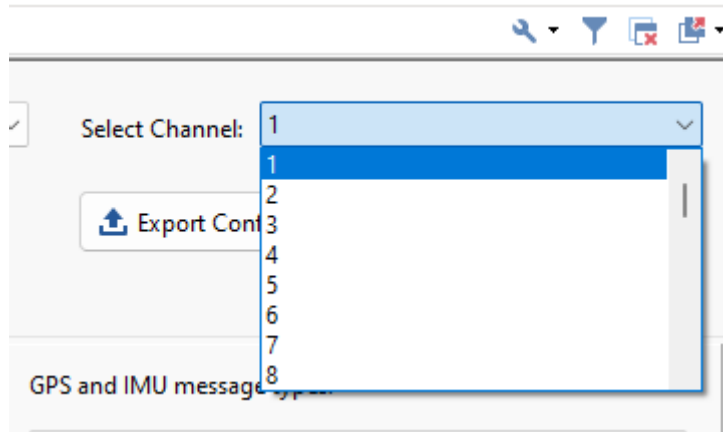
- ◆
- (1)



- (2)



- ◆



(1)

CAN GPS IMU

Controller Type: CAN

Arbitrate Baud(Kbps): 1000

Arbitration Period Time: Sample point 80% BRP=1 TEG1=31 TEG2=8

Arbitrate Field SJW: 1

Terminal resistor activation

Automatically restore from Busoff state

GPS and IMU message types: DLC=8(EXT)

Data Baud(Kbps): 2000

Data Period Time: Sample point 80% BRP=1 TEG1=15 TEG2=4

Data Field SJW: 1

OK

GPS and IMU message types:

DLC=8(EXT)

DLC=8(STD)

DLC=8(EXT)

Data Baud(Kbps):

CAN GPS IMU

Controller Type: CAN FD

GPS and IMU message types: DLC=15(EXT)

Arbitrate Baud(Kbps): 2000

Data Baud(Kbps): 1000

Time: int 80% BRP=1 TEG1=15 TEG2=4

Arbitration Period Time: Sample point 80% BRP=1 TEG1=31 TEG2=8

Data Period: Sample po

JW:

Arbitrate Field SJW: 1

Data Field S: 1

Terminal resistor activation

Automatically restore from Busoff state

OK

GPS and IMU message types:

- DLC= 15(EXT)
- DLC=8(STD)
- DLC=8(EXT)
- DLC= 15(STD)
- DLC= 15(EXT)

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- (1)
- (2)
- (3)

(4)

The screenshot shows the TSMMASTER software interface with the GPS configuration window open. The window has three tabs: CAN, GPS, and IMU. The GPS tab is selected. The configuration options are as follows:

- Select NMEA statement:**
 - GGA
 - GLL
 - GSA
 - ZDA
 - DHV
 - GST
- GPS Data Reporting Cycle(ms):** 1000
- Choose a positioning satellite system:**
 - GPS
 - BDS
 - GLONASS
- GPS data reporting ID:** 0x18000464

An "OK" button is located at the bottom left of the window.



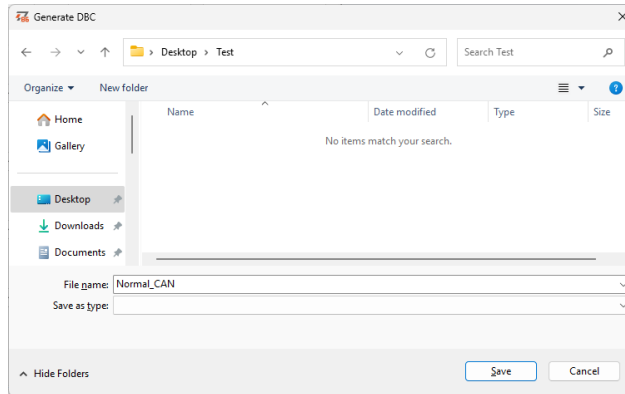
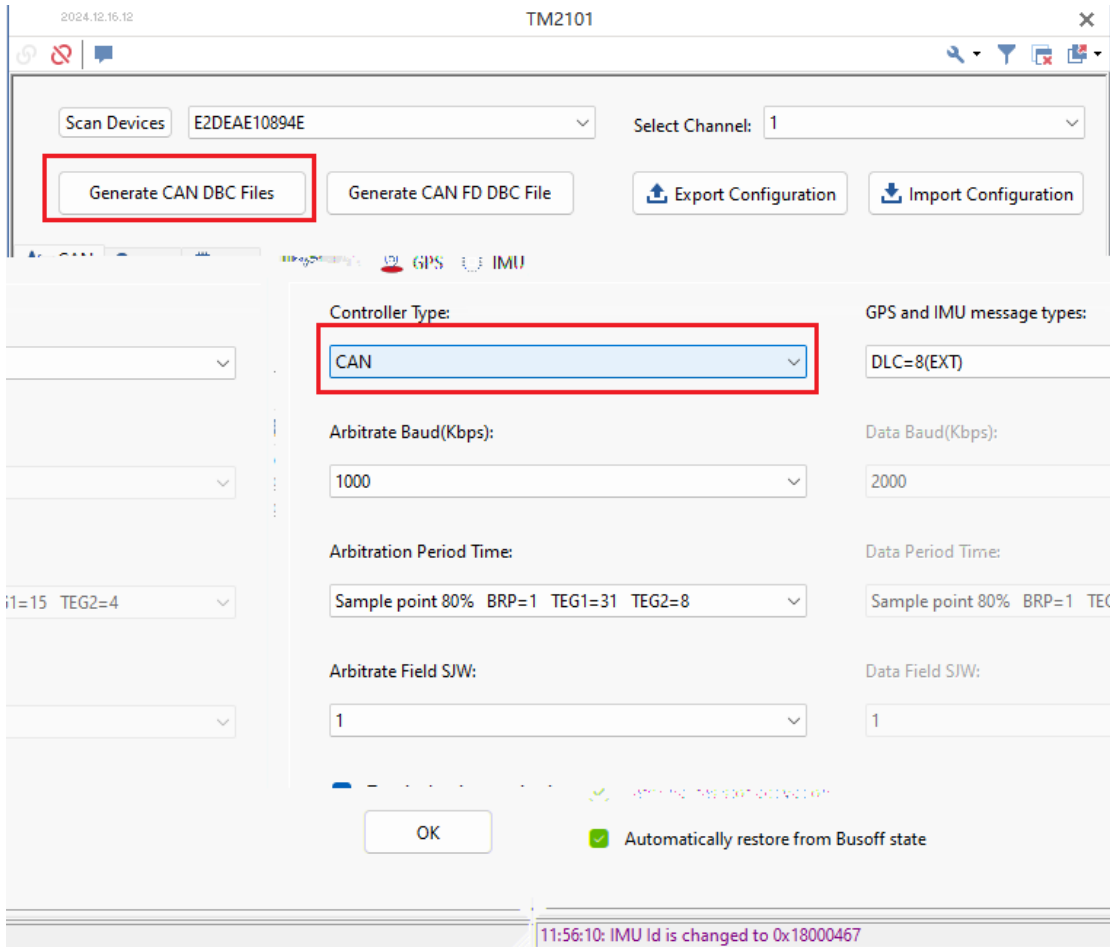
(1)

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(3)

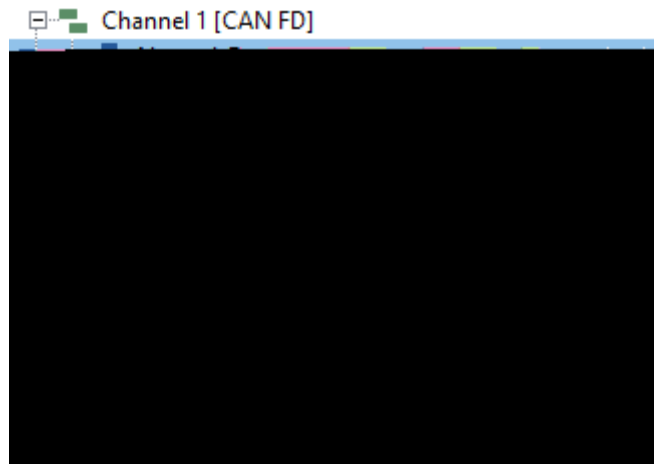
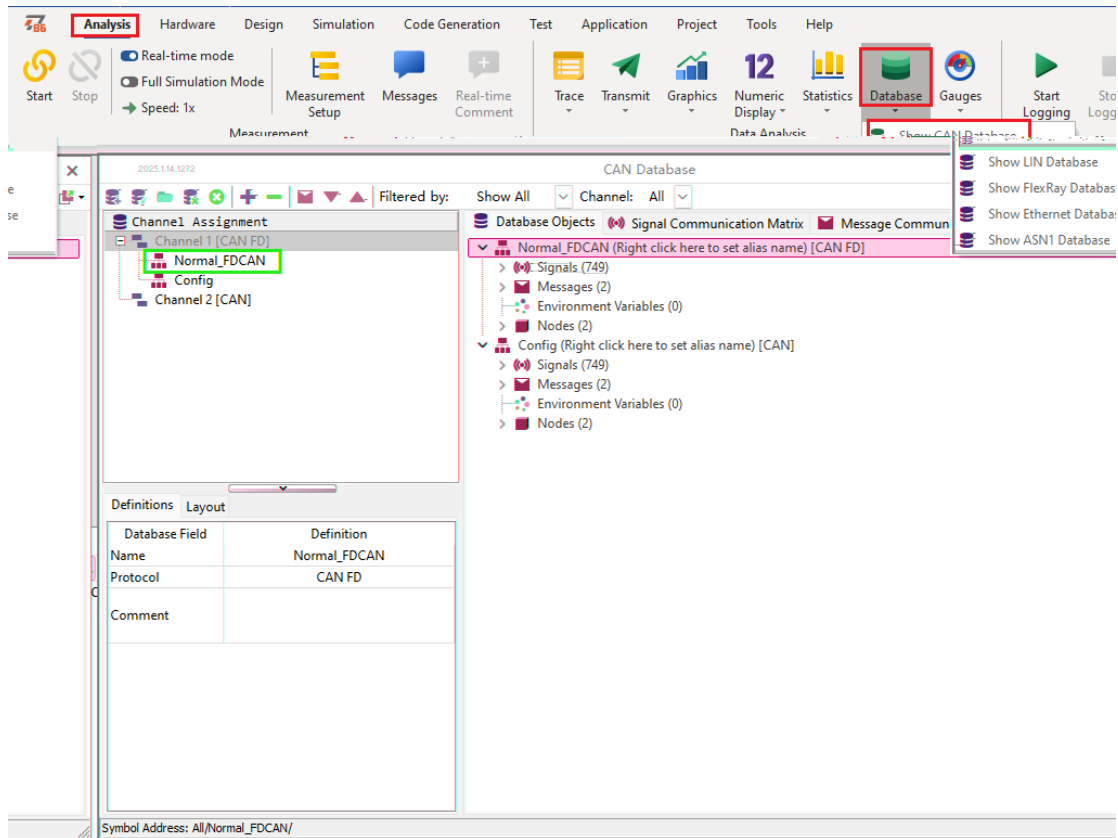
(4)



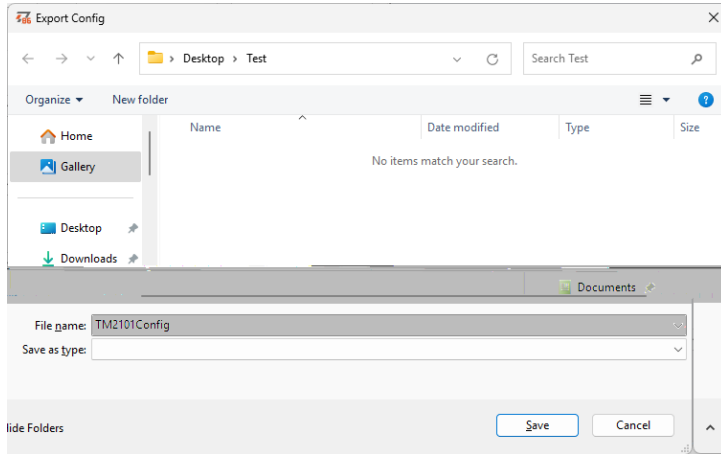


(2)

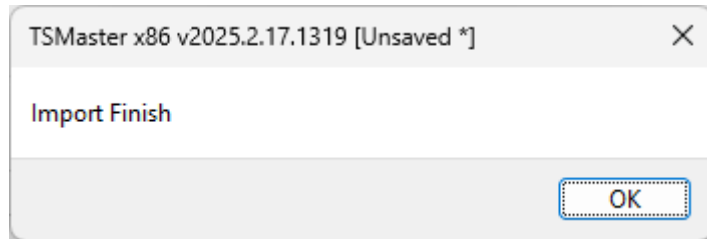
(3)



(1)



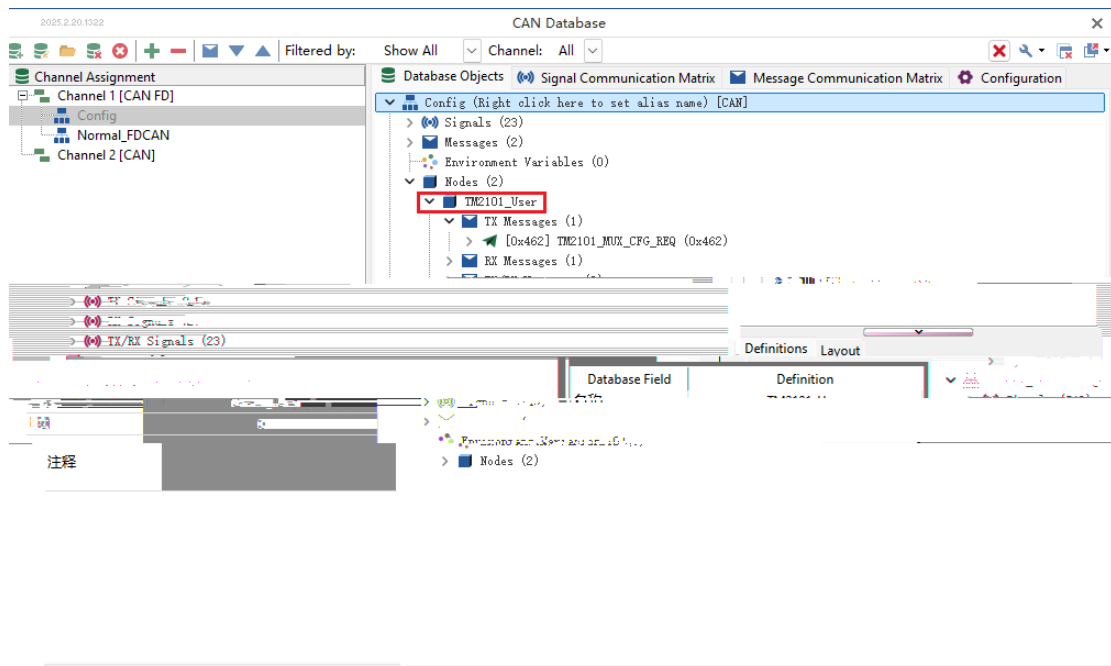
(2)

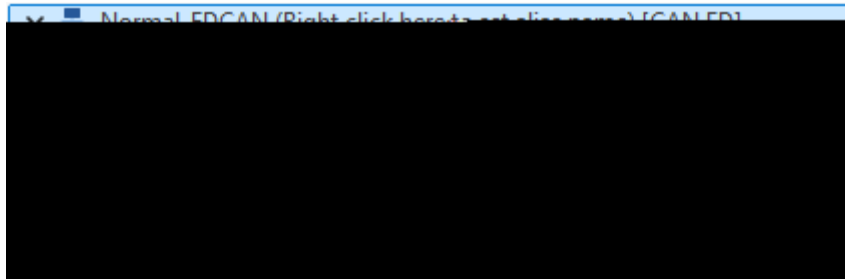


0HVVDJH 3DUVLQJ

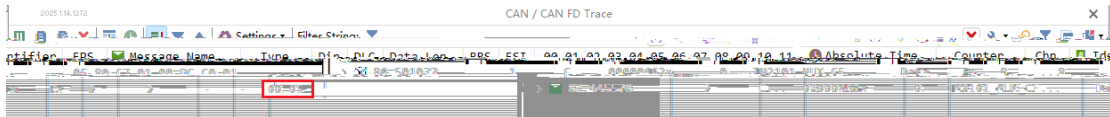
'%&LOH 'HVFULSWLRQ

- Config.dbc
- Normal_bxCAN.dbc
- Normal_FDCAN.dbc

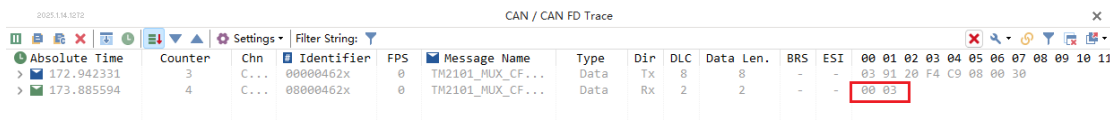




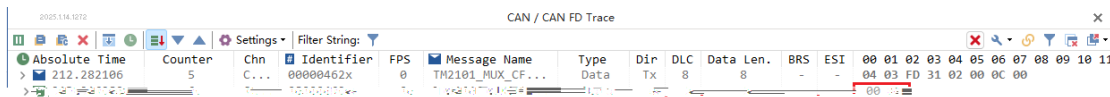
(1)



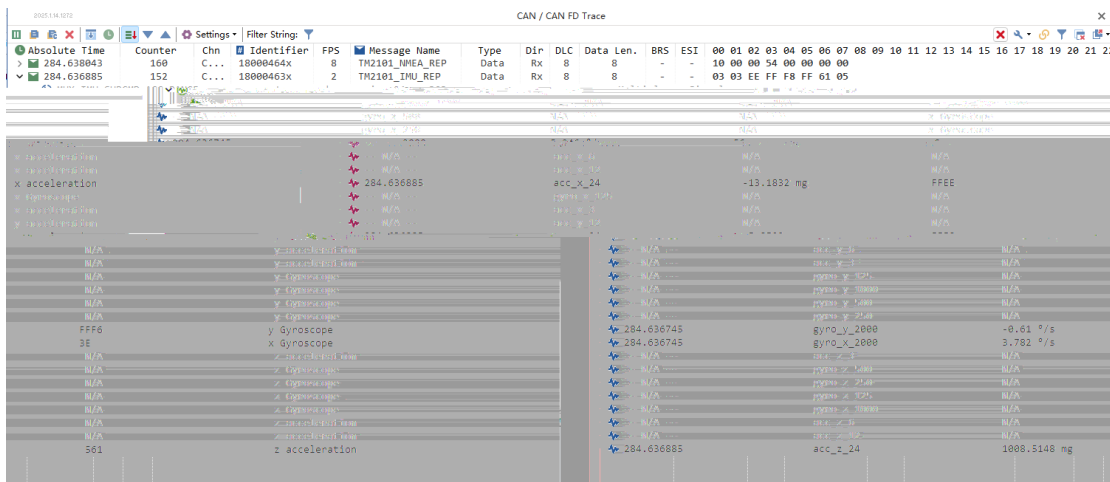
(2)



(3)



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** \$HVVDJH



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*/0HVVDJH



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970HVVDJH



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= '\$HVVDJH



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'+0HVVDJH



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8 708HVVDJH



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* 607H V V D J H



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,QVSHFWLRQ DQG ODLQWHQDQFH

	humidity. (Including the internal humidity of enclosed environments)	humidity must be within the range of 10% to 90%	the humidity and ensure that the ambient humidity within the acceptable range.
	Check for the accumulation of dust, powder, salt, and metal shavings	No accumulation	Clean and protect the equipment.
	Check for any contact with water, oil, or chemical sprays on the equipment	No contact	Clean and protect the equipment if necessary.
	Check for the presence of corrosive or flammable gases in the equipment area	No presence	Inspect by the smell, or using a sensor.
	Check for levels of vibration and shock	Vibration and shock are within the acceptable range	Install padding or other shock-absorbing devices if necessary.
	Check for noise sources near the equipment	No significant noise source	Isolate the equipment from noise sources or protect the equipment.
Wiring Installation	Check the crimped connectors in the external wiring	Ensure enough space between the connectors	Visually inspect and adjust if necessary.
	Check for damage in the external wiring	No damage	Visually inspect and replace the wiring if necessary.

Software

Hardware

12/4/8/12 - channel CAN FD/CAN in USB/PCIe device

Support CAN FD and advanced CAN protocols

16/6 - channel LIN in USB/PCIe device

MCU firmware/ECU flashing / OBD/ECU calibration

Multi channel FlexRay / CAN FD to USB/PCIe device

Embedded code generation (application)

Encrypted release, Logging and bus replay

Multi channel automotive Ethernet / CAN FD to USB/PCIe device

En

Technical programming / Residual bus simulation

Automotive Ethernet media conversion device (T1 to Tx)

Gr

Stand Python scripting

Multi channel CAN FD/Ethernet/LIN data logger